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UTILITY PATENT APPLICATION TRANSMITTAL

(Only for new nonprovisional applications under 37 C.F.R. § 1.53(b))

Attorney Docket No.	ACO2733US
First Inventor or Application Identifier	Daniel SPITZER
Title	METHODS OF APPLYING COLOUR MEASUREMENT ....
Express Mail Label No.	EM432406808US

APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents.

ADDRESS TO: Assistant Commissioner for Patents
Box Patent Application
Washington, DC 20231

1. [X] * Fee Transmittal Form *(e.g., PTO/SB/17)*
   (Submit an original and a duplicate for fee processing)

2. [X] Specification [*Total Pages* 32]
   (preferred arrangement set forth below)
   - Descriptive title of the Invention
   - Cross References to Related Applications
   - Statement Regarding Fed sponsored R & D
   - Reference to Microfiche Appendix
   - Background of the Invention
   - Brief Summary of the Invention
   - Brief Description of the Drawings *(if filed)*
   - Detailed Description
   - Claim(s)
   - Abstract of the Disclosure

3. [X] Drawing(s) *(35 U.S.C. 113)* [*Total Sheets* 2]

4. Oath or Declaration (unsigned) *Total Pages* 3]
   a. [ ] Newly executed (original or copy)
   b. [ ] Copy from a prior application (37 C.F.R. § 1.63(d))
      (for continuation/divisional with Box 16 completed)
      i. [ ] DELETION OF INVENTOR(S)
         Signed statement attached deleting inventor(s) named in the prior application, see 37 C.F.R. §§ 1.63(d)(2) and 1.33(b).

NOTE FOR ITEMS 1 & 13: IN ORDER TO BE ENTITLED TO PAY SMALL ENTITY FEES, A SMALL ENTITY STATEMENT IS REQUIRED (37 C.F.R. § 1.27), EXCEPT IF ONE FILED IN A PRIOR APPLICATION IS RELIED UPON (37 C.F.R. § 1.28).

5. [ ] Microfiche Computer Program *(Appendix)*

6. Nucleotide and/or Amino Acid Sequence Submission *(if applicable, all necessary)*
   a. [ ] Computer Readable Copy
   b. [ ] Paper Copy (identical to computer copy)
   c. [ ] Statement verifying identity of above copies

ACCOMPANYING APPLICATION PARTS

7. [ ] Assignment Papers (cover sheet & document(s))
8. [ ] 37 C.F.R.§3.73(b) Statement [ ] Power of Attorney *(when there is an assignee)*
9. [ ] English Translation Document *(if applicable)*
10. [ ] Information Disclosure Statement (IDS)/PTO-1449 [ ] Copies of IDS Citations
11. [ ] Preliminary Amendment
12. [X] Return Receipt Postcard (MPEP 503) *(Should be specifically itemized)*
13. [ ] * Small Entity Statement(s) (PTO/SB/09-12) [ ] Statement filed in prior application, Status still proper and desired
14. [ ] Certified Copy of Priority Document(s) *(if foreign priority is claimed)*
15. [ ] Other: ....
....
....

16. If a CONTINUING APPLICATION, *check appropriate box, and supply the requisite information below and in a preliminary amendment:*
[ ] Continuation [ ] Divisional [ ] Continuation-in-part (CIP) of prior application No: _____/_____
Prior application information: Examiner_____ Group / Art Unit: _____

For CONTINUATION or DIVISIONAL APPS only: The entire disclosure of the prior application, from which an oath or declaration is supplied under Box 4b, is considered a part of the disclosure of the accompanying continuation or divisional application and is hereby incorporated by reference. The incorporation <u>can only</u> be relied upon when a portion has been inadvertently omitted from the submitted application parts.

17. CORRESPONDENCE ADDRESS

[ ] Customer Number or Bar Code Label
(Insert Customer No. or Attach bar code label here)
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Signature	Richard P. Fennelly	*Date*	OCT 5 2000

Express Mail Label No.: EM432406808US

FEE TRANSMITTAL
for FY 2000

Patent fees are subject to annual revision.
Small Entity payments must be supported by a small entity statement, otherwise large entity fees must be paid. See Forms PTO/SB/09-12.
See 37 C.F.R. §§ 1.27 and 1.28.

Complete if Known	
Application Number	
Filing Date	
First Named Inventor	Daniel SPTIZER
Examiner Name	
Group / Art Unit	
Attorney Docket No.	AC02733US

TOTAL AMOUNT OF PAYMENT ($) 1286.00

METHOD OF PAYMENT (check one)

1. [X] The Commissioner is hereby authorized to charge indicated fees and credit any overpayments to:

Deposit Account Number: 01-1350

Deposit Account Name: Akzo Nobel Inc.

[X] Charge Any Additional Fee Required Under 37 CFR §§ 1 16 and 1.17

2. [ ] Payment Enclosed:
   [ ] Check [ ] Money Order [ ] Other

FEE CALCULATION

1. BASIC FILING FEE

Large Entity Fee Code	Fee ($)	Small Entity Fee Code	Fee ($)	Fee Description	Fee Paid
101	690	201	345	Utility filing fee	
106	310	206	155	Design filing fee	
107	480	207	240	Plant filing fee	
108	690	208	345	Reissue filing fee	
114	150	214	75	Provisional filing fee	

SUBTOTAL (1) ($) 710.00

2. EXTRA CLAIM FEES

	Extra Claims	Fee from below	Fee Paid
Total Claims	37 -20** = 17	X	306.0
Independent Claims	3 - 3** = —	X	—
Multiple Dependent			270.0

**or number previously paid, if greater; For Reissues, see below

Large Entity Fee Code	Fee ($)	Small Entity Fee Code	Fee ($)	Fee Description
103	18	203	9	Claims in excess of 20
102	78	202	39	Independent claims in excess of 3
104	260	204	130	Multiple dependent claim, if not paid
109	78	209	39	** Reissue independent claims over original patent
110	18	210	9	** Reissue claims in excess of 20 and over original patent

SUBTOTAL (2) ($) 576.00

FEE CALCULATION (continued)

3. ADDITIONAL FEES

Large Entity Fee Code	Fee ($)	Small Entity Fee Code	Fee ($)	Fee Description	Fee Paid
105	130	205	65	Surcharge - late filing fee or oath	
127	50	227	25	Surcharge - late provisional filing fee or cover sheet.	
139	130	139	130	Non-English specification	
147	2,520	147	2,520	For filing a request for reexamination	
112	920*	112	920*	Requesting publication of SIR prior to Examiner action	
113	1,840*	113	1,840*	Requesting publication of SIR after Examiner action	
115	110	215	55	Extension for reply within first month	
116	380	216	190	Extension for reply within second month	
117	870	217	435	Extension for reply within third month	
118	1,360	218	680	Extension for reply within fourth month	
128	1,850	228	925	Extension for reply within fifth month	
119	300	219	150	Notice of Appeal	
120	300	220	150	Filing a brief in support of an appeal	
121	260	221	130	Request for oral hearing	
138	1,510	138	1,510	Petition to institute a public use proceeding	
140	110	240	55	Petition to revive - unavoidable	
141	1,210	241	605	Petition to revive - unintentional	
142	1,210	242	605	Utility issue fee (or reissue)	
143	430	243	215	Design issue fee	
144	580	244	290	Plant issue fee ·	
122	130	122	130	Petitions to the Commissioner	
123	50	123	50	Petitions related to provisional applications	
126	240	126	240	Submission of Information Disclosure Stmt	
581	40	581	40	Recording each patent assignment per property (times number of properties)	
146	690	246	345	Filing a submission after final rejection (37 CFR § 1.129(a))	
149	690	249	345	For each additional invention to be examined (37 CFR § 1.129(b))	

Other fee (specify) _____

Other fee (specify) _____

* Reduced by Basic Filing Fee Paid

SUBTOTAL (3) ($)

SUBMITTED BY

		Complete (if applicable)	
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METHODS APPLYING COLOUR MEASUREMENT BY MEANS OF AN
5 ELECTRONIC IMAGING DEVICE

The invention pertains to methods applying colour measurement by means of an electronic imaging device. More particularly, the invention pertains to a
10 method of determining a colour formula for matching a selected colour measured with an electronic imaging device. The invention is also directed to a method of determining a colour formula for matching a selected colour of a textured material measured with an electronic imaging device. Finally, the invention is directed to a method for checking a selected colour measured with
15 an electronic imaging device with a standard colour sample.

It is well-known to measure selected colours with the aid of colour meters, such as spectrophotometers and tri-stimulus meters . The measured signals may be used for the determination of a colour formula. Thus U.S. 4,813,000 discloses
20 measuring a selected colour with the aid of a tri-stimulus colour analyser and using the measured chromaticity data to search for a colour formula in a databank. A series of articles by W. R. Cramer published in *Fahrzeug + Karosserie*, 9, 1997, 11-12, 1997, and 1-5, 1998, describes commercial applications of measuring a selected colour with the aid of a spectrophotometer
25 and using the measured spectral data to search for a colour formula in a databank. Such methods are especially suitable for use at points of sale where paints have to be available in every colour.

It is also possible to use the measured signals to check the selected colour with
30 a standard colour sample. Such a method is currently used in the printing inks industry.

The human eye is highly sensitive to colour differences. If a colour is to be matched, it is essential that the measurement of the colour be as accurate as
35 possible. High measuring accuracy requires calibration. To this end there are

fixed standards defining colour in terms of standard values, so-called colorimetric data. Most common colorimetric data has been laid down by the Commision International de l'Eclairage (CIE), e.g., CIELab (L^*_{ab}, a^*, b^*), CIEXYZ (X, Y, Z), and CIELUV (L^*_{uv}, u^*, v^*). Spectral measuring data and tri-

5   stimulus measuring data therefore have to be converted to colorimetric data if a spectrophotometer or a tri-stimulus meter is to be calibrated.

The drawback to spectrophotometers is that they are very delicate instruments. Hence a certain expertise is required on the part of the user which is not always

10   available at the aforementioned points of sale. Moreover, spectrophotometers are expensive. A further drawback to spectrophotometers and tri-stimulus meters is that they cannot be used for measuring colour appearance including texture of the material.

15   The invention pertains to a method of determining a colour formula for matching a selected colour measured with an electronic imaging device, which method comprises the following steps:

a) an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colours, the colorimetric data of each of the

20   calibration colours being known;

b) at the same time or in a next step the selected colour is measured with the aid of the electronic imaging device;

c) using a mathematical model, parameters are calculated for converting the measured colour signals of the calibration colours to the known colorimetric

25   data;

d) using the mathematical model and the calculated parameters, the colour signals of the measured selected colour are converted to colorimetric data; and

e) using a databank, the colour formula is determined of which the colorimetric

30   data most closely matches the calculated colorimetric data of the measured selected colour.

The invention has the advantage that it is possible to make use of inexpensive consumer electronics. Consumer electronics often do not have the accurate settings required for specialist applications. The method according to the invention now makes it possible to utilise an inaccurate device for the determination of a colour formula for matching a selected colour and yet achieve a high level of measuring accuracy. In addition, the method can be performed easily by a non-specialist without him needing extensive training. The method according to the invention also makes it possible to measure a specific attribute of the colour appearance, the so-called texture.

In the method according to the invention the term "electronic imaging device" stands for all devices with which an electronic image can be recorded that can be processed with the aid of a computer. Examples of such electronic imaging devices are digital recording devices. Preferably, the electronic imaging device is a digital video camera, a digital camera, a flatbed scanner, a drum scanner, or a manually operated scanner. However, an analogue video camera coupled to a so-called frame grabber which converts the analogue signal to a digital image is also covered by the term "electronic imaging device." Finally, the term "electronic imaging device" also covers multi-spectral-imaging equipment and monochrome cameras with multiple colour filters. Examples of flatbed scanners are the Hewlett Packard 3C, Hewlett Packard Scanjet IIc, Sharp JX450, Agfa Focus Color, and Afga Arcus Plus. Examples of drum scanners are the Howtek D4000, Optronics Color Getter, and LeafScan 45. Examples of digital cameras are the Ricoh RDC 5000, Olympus C-2000Z, and Nikon Coolpix 950. Preferably, a digital camera is employed.

A minimum of two calibration colours is used, i.e. white and black. Optionally, use may be made of grey or neutral colours. For a more accurate conversion of the colour signals of the selected colour to colorimetric data preference is given to including calibration colours other than the neutral colours. The calibration colours may be selected at random. Preferably, use is made of calibration colours distributed over the entire colorimetric colour space. More preferably,

use is made of calibration colours distributed in the vicinity of the selected colour.

In theory, the physical calibration pattern can comprise as many calibration colours as may be present within the image field of the electronic imaging device. The calibration colours are recorded on the pattern in the form of patches. In theory, the calibration patches may have the size of a single pixel. In that case the size of the measuring surface will be equal to the size of the calibration patch. Depending on the electronic imaging device employed, phenomena may occur which require the calibration patch to be bigger than a single pixel. Such phenomena include stability, non-linearity, distortions, reproducibility of positioning, and cross-talk. Generally speaking, between 2 and 1000 calibration colours may be present, preferably 10-500, more preferably 25-150.

Of course, the calibration patches need not be square. Nor do they have to be rectangular or regularly shaped. There is no need to separate the colours, i.e. the colour is allowed to shift gradually.

The support on which the calibration patches are provided may be flat or curved. Preferably, the support is of uniform colour, e.g., white or grey. A clear space may be left around a portion or all of the calibration patches so as to leave the support's surface area visible. The uniform colour of the support may also serve to measure and correct any spatial non-uniformity of the electronic imaging device.

Depending on the measuring accuracy required, it may be preferred to measure the calibration colours and the selected colour simultaneously. In such cases the calibration pattern support may be provided with a recess, e.g., at the centre. Alternatively, a support may be selected which is smaller than the image field, so that the remaining image field can be used to record the selected colour.

Also, within the framework of the present invention it is possible to calibrate beforehand in step a) using a calibration pattern with more than 10 colours, then in step b) carry out a black and white calibration and measure the selected colour simultaneously. This combination of steps is useful in reducing the

5   variation in brightness due to the influence of the light source.

Processing the recorded image, calculating the model parameters, and converting the measured colour signals to colorimetric data is all done by means of computer software. The software indicates the position of the

10   calibration pattern and, optionally, the object to be measured. The software also includes a table listing known colorimetric data for each calibration colour and a mathematical model describing the correlation between the measured colour signals and the colorimetric data. With the aid of the software the model parameters are calculated from the mathematical model. The software then

15   goes on to use the mathematical model and the model parameters to convert the measured signals of the selected colour to colorimetric data.

Colorimetric data may be exemplified by CIE systems such as Lab or XYZ. However, this term is not restricted to CIE systems. It may be possible to use

20   user defined systems.

The mathematical model selected may be any model known to the skilled person. Examples are mentioned in H.R. Kang, *Color Technology for Electronic Imaging Devices*, SPIE Optical Engineering Press, 1997, chapters 3 and 11,

25   and in U.S. 5,850,472. The model may be non-linear or linear. One example of a non-linear model is a 2nd order polynomial having 10 parameters or a 3rd order polynomial having 20 parameters. Preferably, use is made of a linear model. More preferably, the linear model used has 4 model parameters.

30   One example of a linear model having 4 parameters is the following model, where the measured colour signals of the calibration colours, in this case R, G, and B data, are converted to colorimetric data, in this case CIELab data:

$$L_i^* = c_0 + c_1 R_i + c_2 G_i + c_3 B_i,$$

$$a_i{}^* = d_0 + d_1R_i + d_2G_i + d_3B_i,$$

$$b_i{}^* = e_0 + e_1R_i + e_2G_i + e_3B_i,$$

wherein R_i, G_i, B_i, $L_i{}^*$, $a_i{}^*$, and $b_i{}^*$ are the measured signals and the colorimetric data of calibration colour i.

5

Linear regression is used to calculate the model parameters c_0-c_3, d_0-d_3, and e_0-e_3 from the measured RGB data and the known CIELab data of the calibration colours. These model parameters are used to convert the measured RGB data of the selected colour to CIELab data.

10

One example of a non-linear 3rd order polynomial having 20 parameters is:

$$
\begin{aligned}
L_i{}^* = \ & c_0 + c_1R_i + c_2G_i - c_3B_i + c_4R_i{}^2 + c_5G_i{}^2 + c_6B_i{}^2 - c_7R_iG_i - c_8R_iB_i + c_9G_iB_i + \\
& c_{10}R_i{}^3 + c_{11}G_i{}^3 + c_{12}B_i{}^3 + c_{13}R_i{}^2G_i + c_{14}R_i{}^2B_i + c_{15}G_i{}^2R_i + c_{16}G_i{}^2B_i + \\
& c_{17}B_i{}^2R_i + c_{18}B_i{}^2G_i + c_{19}R_iG_iB_i
\end{aligned}
$$

15
$$
\begin{aligned}
a_i{}^* = \ & d_0 + d_1R_i + d_2G_i - d_3B_i + d_4R_i{}^2 + d_5G_i{}^2 + d_6B_i{}^2 - d_7R_iG_i - d_8R_iB_i + d_9G_iB_i + \\
& d_{10}R_i{}^3 + d_{11}G_i{}^3 + d_{12}B_i{}^3 + d_{13}R_i{}^2G_i + d_{14}R_i{}^2B_i + d_{15}G_i{}^2R_i + d_{16}G_i{}^2B_i + \\
& d_{17}B_i{}^2R_i + d_{18}B_i{}^2G_i + d_{19}R_iG_iB_i
\end{aligned}
$$

$$
\begin{aligned}
b_i{}^* = \ & e_0 + e_1R_i + e_2G_i - e_3B_i + e_4R_i{}^2 + e_5G_i{}^2 + e_6B_i{}^2 - e_7R_iG_i - e_8R_iB_i + e_9G_iB_i + \\
& e_{10}R_i{}^3 + e_{11}G_i{}^3 + e_{12}B_i{}^3 + e_{13}R_i{}^2G_i + e_{14}R_i{}^2B_i + e_{15}G_i{}^2R_i + e_{16}G_i{}^2B_i + \\
& e_{17}B_i{}^2R_i + e_{18}B_i{}^2G_i + e_{19}R_iG_iB_i
\end{aligned}
$$

20

Linear regression is used to calculate the model parameters c_0-c_{19}, d_0-d_{19}, and e_0-e_{19} from the measured RGB data and the known CIELab data of the calibration colours. These model parameters are used to convert the measured RGB data of the selected colour to CIELab data.

25

Notwithstanding the above, it is possible to lend greater weight to the calibration colours in the vicinity of the selected colour when calculating the model parameters. In the case of the above example of a linear model having 4 parameters, this means that during the linear regression each calibration colour

30   is given a weighing factor based on the distance in the RGB colour space between the calibration colour in question and the selected colour. In the linear regression procedure the following sum of squares is minimised:

$$\sum_{i=1}^{n} w_i (y_i - \hat{y}_i)^2$$

Written out, this sum is as follows:

$$\sum_{i=1}^{n} \left(L_i^* - c_0 - c_1 R_i - c_2 G_i - c_3 B_i\right)^2 \left((R_i - R)^2 + (G_i - G)^2 + (B_i - B)^2\right)^{-2}$$

$$\sum_{i=1}^{n} \left(a_i^* - d_0 - d_1 R_i - d_2 G_i - d_3 B_i\right)^2 \left((R_i - R)^2 + (G_i - G)^2 + (B_i - B)^2\right)^{-2}$$

5 $$\sum_{i=1}^{n} \left(b_i^* - e_0 - e_1 R_i - e_2 G_i - e_3 B_i\right)^2 \left((R_i - R)^2 + (G_i - G)^2 + (B_i - B)^2\right)^{-2}$$

wherein

n : is the number of calibration colours

R, G, B: are the measured signals of the selected colour

10   Alternatively, it is possible to use the calibration colours in the vicinity of the selected colour for interpolation.

If so desired, grey balancing may be performed on the signals measured for black, white, and grey according to the formula R=G=B=f(L*) or a comparable

15   value for L* in a different colorimetric system. Such grey balancing is described in H.R. Kang, *Color Technology for Electronic Imaging Devices*, SPIE Optical Engineering Press, 1997, chapter 11. Examples of algorithms suitable for use are:

$R_{ig} = f_1 + f_2 \cdot L_{ig}^*$

20    $R_{ig} = f_1 + f_2 \cdot L_{ig}^* + f_3 \cdot (L_{ig}^*)^2$

$R_{ig} = f_1 + f_2 \cdot L_{ig}^* + f_3 \cdot \log(L_{ig}^*)$

wherein R_{ig} is the measured signal and L_{ig}^* is the colorimetric value of the white, grey, and black calibration colours.

25   Alternatively, if so desired, an offset correction of the measured data for black and white may be performed according to the following formula:

$$R_c = ((R - R_b)/(R_w - R_b)) \times 255$$
$$G_c = ((G - G_b)/(G_w - G_b)) \times 255$$
$$B_c = ((B - B_b)/(B_w - B_b)) \times 255$$

wherein

R_c, G_c, B_c = the corrected signals for the selected colour

R, G, B = the measured signals for the selected colour

R_w, G_w, B_w = the measured signals for white

5   R_b, G_b, B_b = the measured signals for black

In the final step of the method according to the invention a databank is used to determine a colour formula having colorimetric data most closely matching the calculated colorimetric data of the measured selected colour. One measure of

10   the colour difference between the colour formula and the selected colour is, e.g., the following mathematical algorithm:

$$\Delta E^*_{ab} = \sqrt{\left(\left(\Delta L^*\right)^2 + \left(\Delta a^*\right)^2 + \left(\Delta b^*\right)^2\right)}$$

wherein

ΔE^*_{ab} is the colour difference according to CIE

15   $\Delta L^* = L^*_1 - L^*_2$

$\Delta a^* = a_1^* - a_2^*$

$\Delta b^* = b_1^* - b_2^*$

1 = the calculated colorimetric data of the selected colour

2 = the colorimetric data of the colour formula from the databank

20   The smaller the colour difference ΔE_{ab}^* is, the better the match between the selected colour and the colour formula will be.

Colour formulas can be determined in a number of ways, i.e. by means of search procedures, calculations, or combinations of the two. For example, use

25   may be made of a databank comprising colour formulas having colorimetric data linked thereto. Using the calculated colorimetric data of the measured selected colour, the most closely matching colour formula can be found. Alternatively, it is possible to use a databank having colour formulas with spectral data linked thereto. Known calculation methods can be used to

30   calculate the colorimetric data of the colour formulas and compare them. Also, a databank can be used in which the absorption and reflection data, the so-called

K and S data, of pigments are stored. Using K and S data in combination with pigment concentrations makes it possible to calculate the colour formula of which the colorimetric data most closely match the colorimetric data of the measured selected colour. The methods in question have been described in

5   detail in D.B. Judd et al., *Color in Business, Science and Industry*. It is possible to combine the aforesaid search and calculation methods.

Phenomena such as light source metamerism, angular metamerism, and texture will affect the colour matching.

10

Light source metamerism is a phenomenon where under a single light source, e.g., daylight, the observed colours of two objects may be the same visually, while under some other light source, e.g., fluorescent light, the colours differ. This can be taken into account by measuring under two light sources with

15   different emission spectra. In the method according to the invention, advantageous use is made of an electronic imaging device, with recordings being made of the selected colour and the calibration colours under different light sources. The software needed to process different measurements of the same object is known to the skilled person.

20

Textured materials, such as metallic and pearlescent paints, are characterised in that the appearance of the colour changes as the angle of observation and/or exposure angle changes (angular metamerism). For proper measurement of such colours it is therefore essential to determine the colour at at least two

25   different angles. In this process it is advantageous to make use of the method according to the invention. An electronic imaging device makes it possible to measure the colour of an object in any one of the following ways or combinations thereof:

-        At least two recordings are made with the electronic imaging device while

30   the object moves within the image field of the device ;

-        At least two recordings are made with the electronic imaging device while the device moves vis-à-vis the object;

-    At least two recordings are made with the electronic imaging device while a light source is moved vis-à-vis the object; or

-    One recording is made with the electronic imaging device of a flat or curved section of the object when the device is able to discriminate in a

5   single image between data at different angles.

The software required to process different measurements of the same object is known to the skilled person.

Another characteristic of materials, such as special effect paints, is texture.

10   Texture can be defined as an arrangement of small areas having a specific colour and/or shape. It was found that by using image processing methods known as such the texture of a special effect paint can be determined from recordings made with an electronic imaging device. One way of characterising texture is by means of texture parameters. Commercially available image

15   processing packages, e.g., "Optimas," make it possible to calculate such texture parameters using the recording. An example of such calculations is given below. Needless to say, said example should not be construed as limiting the present invention in any way.

20   The recording of the measured selected colour is used to determine the average brightness. Selected are areas in the recording which have much higher than average brightness. If so desired, it can be determined which areas overlap or adjoin and to separate those areas using software. Each selected area has its circumference and surface area calculated. This gives the average

25   circumference, the average surface area, and the accompanying standard deviations for the measured selected colour. Optionally, calculations such as averaging and filtering pixels and/or pixel groups may also be included.

If so desired, the texture measurement can be calibrated by applying one or

30   more rulers to the calibration pattern.

For matching textured materials such as special effect paint, the method according to the invention provides the possibility of linking the colour formulas

in a databank not only to colorimetric data but also to texture parameters or recordings from which texture parameters can be calculated. Using these parameters or recordings the colour formula most closely matching the selected colour also in terms of texture can be found in the databank. One example of an
5   algorithm for finding the most closely matching colour formula which is also closest to the selected colour in terms of texture is as follows:

$$\Delta T = \sqrt{w_1 \Delta T_1^2 + w_2 \Delta T_2^2 + K + w_i \Delta T_i^2}$$

wherein

w_{1-i} = weighing factors

10   T_{1-i}= texture parameters

It is also possible to calculate an overall parameter, e.g. $\Delta Q = f(\Delta E, \Delta T)$.

The method according to the invention can be applied at points of sale which have to be able to supply paint in any colour desired. A colour formula is made
15   up of quantities of mixing colours, master paints and/or pigment pastes. Using the colour formula, the paint can be prepared in a dispenser. In the car repair sector it is customary to employ a set of mixing colours standardised for colour and colour strength. These standardised mixing colours, usually about 40 different colours, are present at the points of sale. From this set of standardised
20   mixing colours any colour of paint desired can be made. In the DIY sector as well as the professional painting industry it is customary to use a set of master paints standardised for colour which often consists of at least one white and/or one clear master colour, i.e. a paint without pigment, optionally supplemented with master paints in a number of different colours, and pigment pastes
25   standardised for colour and colour strength. From this set of master paints any colour desired can be made by adding pigment pastes to the master paint.

The present invention can be used with advantage in the car repair industry. In that case, the method may be carried out as follows. The colour of a car to be
30   repaired is measured using an electronic imaging device. Prior to this or at the same time, a recording is made of a panel on which different calibration colours have been applied. The colorimetric data of the car's colour is calculated.

Software is used to generate the colour formula which after application will give a colour identical to the colour of the car to be repaired. The colour formula is prepared in a dispenser and applied.

5   As stated above, it may be advantageous to perform the calibration colours measurement simultaneously with the measurement of the selected colour. This is the case for instance in the car auto repair industry, where a measuring accuracy of a ΔE^*_{ab} smaller than 1 is required. In that case the method can be carried out such that in one image both a section of the car and the panel with
10   the calibration colours are measured. The process does not require that the calibration panel is actually positioned on the car. It may be mounted somewhere else, providing it is in the same image field as the car during the recording.

15   Optionally, other information may be provided to be recorded with the electronic imaging device. For example, when several patterns are used, a code may be provided on every pattern. When the method of the invention is used in the car industry, information may be provided with regard to the type of car, its year of manufacturing, and other relevant information. This information may be
20   provided in the form of bar codes, dot codes, or alpha-numerical information. A space may be provided on the calibration pattern for this kind of information. However, it is also possible to provide this information at any other place in the body shop as long as it is in the same image field as the car.

25   Since it has now proved possible to also measure the texture of an object with an electronic imaging device, the invention also comprises a method of determining a colour formula for matching a selected colour of textured materials such as special effect paints in which
     a) the selected colour is measured with a spectrophotometer or tri-stimulus
30   meter;
     b) the texture of the selected colour is measured with an electronic imaging
         device; and

c) the measured colour and texture signals are used to determine, in a databank, the colour formula of which the colorimetric data and the texture parameters most closely match those of the selected colour.

5   It is well-known to use a spectrophotometer for measuring a selected colour of a special effect paint and use the spectral measuring data to find the colour formula most closely matching the selected colour in a databank. Such databanks often will have a texture parameter linked to the colour formula, i.e. coarseness, frequently expressed in a numerical range, such as from 0 to 10.

10   This parameter is indicated by the user, who with the aid of swatches will determine the coarseness of the special effect paint at sight. Using a method according to the invention, it is now possible to determine the texture electronically, convert it to a coarseness value, and use this value to find a colour formula in an existing databank which most closely matches the selected

15   colour.

Alternatively, of course, databanks can be adapted or new ones set up in which new texture parameters or recordings are linked to colour formulas.

20   Since special effect paints are used primarily on cars, the above methods are preferably used in the car repair industry.

Finally, the invention pertains also to a method of determining the colour difference of a selected colour measured with an electronic imaging device

25   compared to a standard colour sample, which method comprises the following steps:

a)   an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colours, the colorimetric data of each of the calibration colours being known;

30   b)   at the same time or in a next step the selected colour is measured with the aid of the electronic imaging device;

c)   using a mathematical model, parameters are calculated for converting the measured colour signals of the calibration colours to the known colorimetric data;

d)   using the mathematical model and the calculated parameters, the colour

5   signals of the measured selected colour are converted to colorimetric data; and

e)   the colorimetric data of the selected colour are compared to the colorimetric data of a standard colour sample.

10   The colorimetric data of the standard colour sample can be available in a software program. It is also possible to measure the standard colour sample before, simultaneously, or after the measurement of the selected colour. This method is preferably used in the printing inks industry.

15   All three methods of the present invention are not restricted to but are preferably used in the paint or printing inks industry.

The invention will be elucidated with reference to the following examples.

Examples

The measurements in these examples were performed using two different calibration patterns, both on an A4-size support. The calibration colours of the two calibration patterns first had their colorimetric data determined with the aid of spectrophotometers:

Calibration pattern 1 (see figure 1):
- 65 calibration colours distributed over the entire colour space
- The colours are from the Sikkens 3031 Color Collection

The L*, a*, and b* data of the 65 calibration colours were measured with the HunterLab UltraScan spectrophotometer with D/8 geometry. The L*, a*, and b* (daylight D65, 10°-observer) data is listed in Table 1.

Calibration pattern 2 (see figure 2):
- 37 calibration colours distributed over part of the colour space (0<a*<50; 0<b*<50; 15<L*<65). The neutral colours (white/ grey/ black) are present in duplicate (colour nos. 1, 2, 6, 7, 8, 13, 14, 15, 18, and 19).
- The colours are selected from the Sikkens Car Refinishes Color Map (Autobase colours)

The 37 calibration colours were measured with different spectrophotometers, among others the Macbeth CE 730-GL, at three angles, 45/0, 45/20, and 45/-65 geometry. The spectral data was transformed mathematically to D/8 geometry. The calculated L*, a*, and b* (scanner light source of the Hewlett Packard Scanjet 5P flatbed scanner, 10°-observer) data is listed in Table 2.

Example 1

A Hewlett Packard 3C flatbed scanner was used to measure the colour of calibration pattern 1 and 149 unknown colours. The method involved each unknown colour being measured simultaneously with the calibration pattern.

The result of the measurements in other words was 149 colour images of calibration pattern 1, each time with one of the 149 unknown colours in the position of the unknown colour (see pattern 1, "unknown"). Using the linear model with 4 parameters and the weighing algorithm as described above, the

5   colorimetric data of the 149 unknown colours was calculated.

In addition, the colorimetric data of the 149 unknown colours was measured with the aforesaid Hunterlab Ultrascan spectrophotometer with D/8 geometry (daylight D65, 10°-observer).

10

Table 3 presents a survey of the data. Columns 2-4 list the colorimetric data as measured with the spectrophotometer, columns 5-7 list the colorimetric data as measured using the scanner, and column 8 lists the colour differences between the spectrophotometer and the scanner colorimetric data. On average, the

15   colour difference ΔE^*_{ab} = 2,26. The median of the colour difference ΔE^*_{ab} = 1,67. The ΔE^*_{ab} 's are also listed in Table 4.

Example 2

Example 1 was repeated, except that the measurement of the calibration

20   pattern took place beforehand. In other words, the outcome of the measurements was one recording of calibration pattern 1 and 149 recordings of the unknown colours without calibration pattern 1.

A survey of the results is also to be found in Table 3. Columns 9-11 list the

25   colorimetric data as determined with the scanner. Column 12 lists the colour difference between the colorimetric data determined with the spectrophotometer and those determined with the scanner. On average, the colour difference ΔE^*_{ab} = 2,23. The median of the colour difference ΔE^*_{ab} = 1,61. The ΔE^*_{ab} 's are also listed in Table 4.

30

Examples 3 and 4

Examples 1 and 2 were repeated, except that also grey balancing was performed using the following algorithm $R_{ig} = f_1 + f_2 \cdot L_{ig}^*$. The results are listed in Table 4.

5

Example 5

Example 1 was repeated, except that there was no weighing. The results are listed in Table 4.

10   Example 6

Example 5 was repeated, except that use was made of the model with 20 parameters as described in the text. The results are listed in Table 4.

Discussion of Examples 1-6

15   As is clear from Table 4, Examples 1-6 show that good results can be obtained using the method according to the invention. Depending on the required accuracy, it is possible to choose among the different algorithms. It is clear from Examples 5 and 6 that a method according to the invention can be performed by simultaneously calibrating and employing a model with 4 or 20 parameters.

20   Also, it is shown in Examples 1-2 and 3-4 that there is hardly any difference between calibrating beforehand and simultaneous calibration. This is probably the result of a combination of factors, i.e. the use of the calibration pattern with 65 colours, the mathematical model, and the Hewlett Packard 3C flatbed scanner. It is expected that a change of one or more of these factors will show

25   better results in the simultaneous calibration than in calibrating beforehand.

Example 7

Using a Hewlett Packard Scanjet 5P flatbed scanner, the colour was measured of calibration pattern 2 and 28 unknown colours, in each case with the unknown colour being measured simultaneously with the calibration pattern. The result of

30   the measurements thus was 28 colour images of calibration pattern 2, each time with one of the 28 unknown colours in the position of the unknown colour (see pattern 2, "unknown"). Using the linear model with 4 parameters and the

weighing algorithm as described in the text above, the colorimetric data of the 28 unknown colours was calculated.

In addition, the colorimetric data of the 28 unknown colours was calculated by
5   measuring the colours with the aid of a MacBeth CE 730-GL spectrophotometer, at three angles, 45/0, 45/20, and 45/-65 geometry (scanner light source of the Hewlett Packard Scanjet 5P flatbed scanner, 10°-observer) and transforming the spectral data mathematically to D/8 geometry.

10   Table 5 presents a survey of the measuring data. Columns 2-4 list the colorimetric data as measured with the spectrophotometer, columns 5-7 list the colorimetric data as measured with the scanner, and column 8 lists the colour differences between the spectrophotometer and the scanner colorimetric data. On average, the colour difference ΔE^*_{ab} = 2,20. The median of the colour
15   difference ΔE^*_{ab} = 2,04. The ΔE^*_{ab}'s are also listed in Table 6.

Example 8
Example 7 was repeated, except that the measurement of the calibration pattern took place beforehand. The outcome of the measurements, in other
20   words, was one recording of calibration pattern 2 and 28 recordings of the unknown colours without calibration pattern 2.

A survey of the results is also to be found in Table 5. Columns 9-11 list the colorimetric data as determined with the scanner. Column 12 lists the colour
25   difference between the colorimetric data determined with the spectrophotometer and those determined with the scanner. On average, the colour difference ΔE^*_{ab} = 2,24. The median of the colour difference ΔE^*_{ab} = 2,18. The ΔE^*_{ab}'s are also listed in Table 6.

Examples 9 and 10

Examples 7 and 8 were repeated, except that also grey balancing was performed using the following algorithm $R_{ig} = f_1 + f_2 \cdot L_{ig}^*$. The ΔE_{ab}^* 's are listed in Table 6.

5

Example 11

Example 7 was repeated, except that there was no weighing. The ΔE_{ab}^* 's are listed in Table 6.

10   Example 12

Example 11 was repeated, except that use was made of the model with 20 parameters as described in the text. The ΔE_{ab}^* 's are listed in Table 6.

Discussion of Examples 7-12

15   As is clear from Table 6, Examples 7-12 show that good results can be obtained using the method according to the invention. Depending on the required accuracy, it is possible to choose among the different algorithms. It is clear from Examples 11 and 12 that a method according to the invention can be performed by simultaneously calibrating and employing a model with 4 or 20 parameters.

20   Also, it is shown in Examples 7-8 and 9-10 that there is hardly any difference between calibrating beforehand and simultaneous calibration. This is probably the result of a combination of factors, i.e. the use of the calibration pattern with 37 colours, the mathematical model, and the Hewlett Packard Scanjet 5P flatbed scanner. It is expected that a change of one or more of these factors will

25   show better results in the simultaneous calibration than in calibrating beforehand.

Example 13: Reproducibility

30   One of the 65 calibration patches of pattern 1 (no. 8) was designated as an unknown colour. The colorimetric data of the selected colour was L*=36,56; a*=56,40; and b*= 42,10.

Calibration patch 8 was measured 149 times with the Hewlett Packard 3C flatbed scanner, simultaneously with the 64 known calibration colours. The standard deviation in ΔE^*_{ab} measured over the 149 measuring points was 0,35,

5   which is comparable with the result for a spectrophotometer.

Example 14: Reproducibility

On eof the 37 calibration patches of pattern 2 (no. 26) was designated as an unknown colour. The colorimetric data of the selected colour was L*=34,29; a*=37,55; and b*=33,64.

10

Calibration patch 26 was measured 28 times with the Hewlett Packard 3C flatbed colours scanner, simultaneously with the 36 known calibration patches. The standard deviation of ΔE^*_{ab} measured over the 28 measuring points was

15   0,17, which is of the same order of magnitude as when a spectrophotometer is used.

Table 1

Colorimetric data of calibration pattern 1 measured with the Hunterlab spectrophotometer (daylight D65, 10°-observer)

Calibration patch	Measured data (CIE)		
	L*	a*	b*
1	23,67	31,31	10,69
2	56,60	34,49	13,98
3	50,48	46,72	18,74
4	46,72	53,20	23,01
5	18,33	13,52	8,22
6	39,86	43,11	30,76
7	34,44	46,89	35,06
8	36,56	56,40	42,10
9	39,04	57,47	45,18
10	35,57	32,99	31,27
11	75,67	20,82	29,39
12	57,50	43,64	62,68
13	45,90	18,78	39,32
14	33,76	7,97	17,87
15	70,84	31,22	92,17
16	89,07	5,42	21,46
17	46,29	9,96	46,57
18	68,95	16,82	80,15
19	40,73	3,70	21,99
20	75,78	11,24	91,04
21	85,14	3,28	57,41
22	87,63	8,71	2,00
23	84,96	7,26	12,81
24	90,59	-0,42	6,25
25	89,13	-1,27	1,02
26	88,89	-7,82	-1,62
27	85,73	1,84	-8,11
28	29,52	6,54	0,72
29	21,56	2,52	4,84
30	36,55	0,89	7,92
31	60,78	-3,08	6,28
32	95,23	-0,91	0,93
33	24,68	-6,48	1,02
34	80,28	-0,13	0,06
35	60,92	-0,20	0,27
36	23,45	-0,45	-0,73
37	30,50	0,26	-0,01
38	16,97	0,31	1,37
39	64,60	1,22	67,45
40	27,26	-4,14	20,17
41	54,33	-14,23	51,54

Calibration patch	Measured data (CIE)		
	L*	a*	b*
42	85,41	-14,22	26,69
43	60,75	-12,09	15,68
44	12,02	-0,39	-0,62
45	48,45	-24,08	29,04
46	27,35	-8,37	8,95
47	79,80	-12,99	14,65
48	63,89	-41,61	38,05
49	35,93	-13,81	8,00
50	40,96	-34,26	11,19
51	35,75	-38,78	0,48
52	55,84	-19,84	-5,48
53	26,09	-9,59	-5,56
54	18,92	-8,61	-8,01
55	74,36	-14,83	-15,11
56	46,17	-29,05	-25,64
57	15,61	-6,47	-10,57
58	57,39	-10,71	-17,84
59	35,59	-12,07	-29,64
60	34,45	-12,38	-37,92
61	43,42	-4,46	-22,82
62	34,21	-0,57	-34,86
63	46,34	7,69	-32,94
64	65,16	15,14	-7,60
65	43,99	22,89	-14,27

Table 2

Colorimetric data of calibration pattern 2 measured with a spectrophotometer (scanner light source of the Hewlett Packard Scanjet 5P flatbed scanner, 10°-observer)

5

Calibration patch	Measured data (CIE)		
	L*	a*	b*
1	17,00	-0,07	-0,34
2	26,13	-0,04	-0,20
3	59,55	6,39	43,02
4	44,03	7,81	44,48
5	40,03	8,02	27,87
6	62,52	-0,50	-0,25
7	42,18	0,09	-0,21
8	17,00	-0,07	-0,34
9	59,01	9,63	26,03
10	29,16	8,09	21,43
11	38,01	30,08	35,37
12	39,96	8,00	35,05
13	87,99	-0,35	-0,08
14	26,13	-0,04	-0,20
15	42,18	0,09	-0,21
16	57,48	20,93	39,01
17	45,24	22,82	39,82
18	62,52	-0,50	-0,25
19	87,99	-0,35	-0,08
20	28,77	21,89	23,23
21	39,85	41,15	41,44
22	39,16	25,28	24,48
23	61,21	22,30	22,38
24	59,28	42,37	39,71
25	24,05	7,78	9,13
26	34,29	37,55	33,64
27	44,14	42,56	26,06
28	54,09	42,16	25,65
29	40,45	9,54	6,44
30	58,95	8,08	7,83
31	28,76	43,21	23,63
32	22,42	24,71	9,62
33	40,61	27,92	9,67
34	25,48	39,71	9,94
35	56,69	26,87	6,45
36	43,08	40,55	4,95
37	57,23	41,44	7,64

Table 3
Measuring data of Examples 1 and 2

Colour	Colorimetric data measured with a spectrophotometer			Simultaneous measuring and calibration			ΔE^*_{ab} - real	Calibration precedes measuring			ΔE^*_{ab} - sing
	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real		L*-sing	a*-sing	b*-sing	
1	49,71	6,26	0,11	50,63	6,92	0,86	1,36	50,63	6,92	0,86	1,36
2	13,27	5,73	2,18	15,40	3,76	3,42	3,15	15,19	3,74	3,32	2,99
3	12,29	17,25	2,74	17,00	18,13	8,93	7,82	15,82	17,62	7,81	6,19
4	75,11	8	3,69	75,84	8,14	4,54	1,13	75,70	7,90	4,81	1,27
5	43,97	51,03	15,41	43,88	51,53	13,73	1,75	43,23	50,34	12,91	2,70
6	17,4	24,77	10,24	21,85	30,74	19,46	11,85	21,35	29,57	18,16	10,07
7	25,19	42,36	21,41	29,51	43,82	30,29	9,99	28,22	42,74	28,54	7,75
8	21,8	2,56	1,53	21,47	3,12	4,07	2,62	21,19	3,35	4,51	3,14
9	15,25	15,84	7,62	17,29	13,49	9,31	3,54	16,45	12,63	7,73	3,43
10	34,81	48,8	29,69	36,16	49,38	33,94	4,50	36,27	48,40	32,83	3,49
11	28,71	49,11	30,31	32,81	49,99	37,88	8,65	31,85	48,86	35,69	6,23
12	22,61	27,71	19,84	22,38	26,01	19,17	1,84	21,21	25,84	17,42	3,36
13	28,01	32,31	23,89	26,97	31,06	23,97	1,63	26,25	29,93	22,82	3,15
14	33,22	50,72	37	33,93	51,63	39,50	2,75	33,00	50,40	37,51	0,64
15	82,74	3,55	3,88	83,33	4,56	5,40	1,92	82,89	4,56	5,76	2,14
16	60,42	24,02	22,39	59,17	25,76	19,18	3,86	58,93	24,67	18,77	3,97
17	45,95	24,87	24,61	46,37	24,88	27,82	3,24	45,88	23,54	26,66	2,44
18	43,89	40,09	38,78	48,04	40,80	51,49	13,39	47,48	39,41	50,14	11,93
19	92,39	1,06	3,49	93,71	0,91	2,93	1,44	92,99	1,08	3,31	0,62
20	89,56	4,09	6,44	89,97	4,39	6,68	0,56	89,66	3,98	6,58	0,21
21	86,08	6,9	7,99	86,57	7,62	9,67	1,90	86,23	7,17	9,54	1,58
22	22,57	4,8	6,06	22,31	4,82	7,16	1,14	22,26	4,76	6,96	0,95
23	45,1	7,29	7,86	45,77	7,06	6,39	1,63	45,43	6,42	6,48	1,67
24	75,62	11,53	12,94	75,48	11,59	12,55	0,42	75,12	10,78	12,20	1,17
25	20,1	10,87	10,38	21,58	11,03	11,66	1,96	20,87	10,12	10,39	1,08
26	54	22,28	26,15	55,73	22,25	28,69	3,07	55,44	20,63	27,75	2,72
27	27,56	15,78	18,83	29,02	14,97	21,38	3,05	28,33	14,92	20,43	1,98
28	71,6	4,45	6,08	71,62	4,10	5,75	0,48	71,15	3,60	5,88	0,98
29	88,36	5,09	7,67	88,92	5,33	9,50	1,93	88,52	5,08	9,14	1,48
30	66,31	8,14	11,37	66,53	7,89	11,49	0,35	66,26	7,04	11,45	1,10
31	80,62	12,48	16,75	80,91	12,77	17,68	1,02	80,77	11,85	17,29	0,84
32	8,42	0,57	-0,11	13,47	-0,12	0,05	5,10	12,91	0,16	-0,24	4,51
33	52,34	2,7	5,87	53,51	2,96	6,10	1,23	53,31	2,18	6,31	1,19
34	34,61	6,16	11,87	35,29	6,25	14,68	2,89	35,26	5,53	14,81	3,08
35	27,7	13,56	22,8	29,83	13,66	24,38	2,65	29,47	13,08	23,47	1,95
36	56,51	9,55	21,34	56,69	9,46	19,03	2,32	56,61	9,41	18,95	2,40
37	25,48	1,29	4,75	24,42	1,29	5,55	1,33	24,28	0,82	6,06	1,84
38	80,87	4,88	14,71	81,05	5,35	15,48	0,92	80,71	5,04	15,45	0,77
39	64,96	8,09	23,33	65,17	8,23	22,80	0,58	65,05	7,65	22,88	0,64
40	70,72	13,31	42,15	70,81	12,61	41,30	1,10	70,78	11,54	40,89	2,17
41	51,9	18,98	54,91	53,83	18,12	62,24	7,63	53,87	17,18	62,55	8,09
42	65,68	2,34	9,17	66,02	2,31	9,82	0,73	65,89	1,95	10,19	1,11
43	52,47	2,46	9,1	52,56	2,64	7,81	1,30	52,82	1,95	8,09	1,19
44	89,61	4,12	14,61	90,63	4,20	17,04	2,63	90,35	3,87	16,42	1,98
45	84,56	7,7	26,01	84,59	7,69	26,57	0,56	84,36	7,03	25,77	0,74
46	89,79	0,81	5,19	90,27	0,74	5,92	0,87	89,78	0,97	5,96	0,79

Colour	Colorimetric data measured with a spectrophotometer			Simultaneous measuring and calibration			ΔE^*_{ab} - real	Calibration precedes measuring			ΔE^*_{ab} - sing
	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real		L*-sing	a*-sing	b*-sing	
47	76,67	1,44	9,09	77,02	1,49	9,27	0,40	76,42	1,33	9,33	0,36
48	45,51	1,92	9,69	46,29	2,17	8,23	1,67	45,81	1,51	8,62	1,19
49	81,64	4,39	21,07	82,05	4,51	21,75	0,80	81,61	4,15	21,33	0,35
50	81,88	1,99	11,52	82,04	1,83	11,48	0,23	81,44	1,68	11,41	0,55
51	70,97	1,77	18,31	71,40	1,77	18,76	0,62	71,19	1,20	18,94	0,87
52	80,28	2,62	20,73	80,64	2,57	21,40	0,76	80,10	2,34	21,11	0,51
53	85,34	2,93	22,93	85,92	2,59	24,07	1,32	85,68	2,11	23,30	0,97
54	65,59	5,37	49,99	66,54	5,22	55,36	5,45	66,52	4,23	55,48	5,69
55	54,62	7,61	54,69	52,93	8,17	59,01	4,67	53,21	6,95	59,06	4,64
56	70,45	1,02	42,48	71,84	1,05	43,87	1,97	71,84	0,07	43,51	1,98
57	89,88	0,18	9,66	90,55	-0,04	10,52	1,11	90,15	0,15	10,16	0,57
58	88,51	0,77	13,07	89,11	0,70	14,58	1,63	88,63	0,59	13,95	0,91
59	77,02	-0,37	14,1	77,40	-0,19	14,30	0,46	76,71	-0,51	14,13	0,34
60	46,16	-0,62	20,09	46,11	-0,19	19,42	0,80	45,81	-0,92	19,70	0,60
61	78,14	-1,25	30,03	79,29	-1,13	31,39	1,78	78,76	-1,52	30,90	1,10
62	92,66	-0,15	8,14	94,21	-0,12	8,50	1,59	93,93	0,12	8,62	1,38
63	85,33	-0,16	10,42	85,99	-0,05	11,57	1,33	85,65	-0,12	11,68	1,30
64	66,7	-1,31	11,69	66,72	-1,12	12,70	1,03	66,81	-1,49	13,05	1,37
65	55,97	-1,72	9,92	56,88	-1,59	9,68	0,95	56,67	-2,35	10,19	0,98
66	45,98	-6,41	28,68	45,07	-5,61	27,82	1,48	45,32	-6,51	29,05	0,77
67	87,22	-1,25	4,43	87,59	-1,36	4,86	0,58	87,10	-1,28	4,92	0,51
68	52,72	-1,9	5,23	53,73	-1,43	5,22	1,11	53,32	-2,10	5,69	0,78
69	71,08	-1,71	5,96	71,36	-1,46	5,91	0,38	70,86	-1,95	6,30	0,47
70	30,92	-2,65	8,69	30,90	-3,12	9,87	1,27	30,76	-3,57	9,93	1,55
71	35,23	-7,34	28,35	36,88	-8,86	30,92	3,41	36,96	-9,49	31,81	4,42
72	55,65	-5,3	9,65	56,01	-5,30	8,96	0,78	55,73	-5,89	9,53	0,61
73	66,67	-5,66	9,97	66,01	-5,67	10,96	1,19	66,06	-6,09	11,48	1,68
74	75,32	-6,33	11,78	74,95	-5,62	10,93	1,17	74,20	-5,61	11,10	1,49
75	85,09	-7,32	12,63	85,21	-7,00	12,84	0,40	84,45	-6,65	13,03	1,01
76	35,1	-7,84	15,88	34,77	-9,59	16,72	1,97	34,65	-10,40	17,03	2,84
77	83,16	-4,27	6,37	84,00	-4,35	7,25	1,22	83,26	-4,15	7,53	1,17
78	57,75	-4,28	6,42	58,14	-3,93	6,13	0,60	57,86	-4,41	6,64	0,28
79	43,77	-2,11	2,4	44,83	-0,79	2,25	1,70	43,86	-1,77	2,16	0,43
80	62,94	-17,03	21,53	62,46	-17,78	18,89	2,78	61,96	-18,20	19,95	2,20
81	92,95	-1,12	1,25	95,73	-0,68	1,26	2,82	94,11	-0,53	1,94	1,47
82	85,51	-10,69	10,42	86,08	-10,21	11,20	1,07	85,06	-9,66	11,58	1,62
83	71,5	-13,48	12,33	70,53	-13,50	10,96	1,68	69,83	-13,62	11,40	1,92
84	48,62	-15,07	12,12	48,97	-13,92	8,73	3,59	48,42	-14,40	9,43	2,78
85	40,29	-19,75	15,51	39,53	-21,46	16,39	2,07	39,63	-21,59	17,19	2,58
86	36,69	-31,82	23,66	36,32	-36,81	23,26	5,02	36,05	-36,72	24,58	5,03
87	46,08	-2,07	1	47,04	-1,10	0,13	1,61	46,37	-1,81	0,36	0,75
88	92,14	-4,27	3,62	93,42	-3,80	3,86	1,38	92,36	-3,44	3,99	0,93
89	64,1	-9,61	6,11	63,08	-9,95	6,58	1,17	62,78	-10,46	6,86	1,74
90	77,38	-11,04	7,27	76,38	-9,96	6,19	1,83	76,10	-9,60	6,46	2,09
91	84,65	-13,66	8,73	84,28	-13,15	8,43	0,70	84,55	-13,32	8,46	0,44
92	20,03	-13,51	6,95	21,05	-10,84	6,42	2,91	20,82	-11,13	6,60	2,53
93	16,47	-5,88	3,55	17,88	-4,26	3,74	2,15	17,66	-4,44	3,93	1,91
94	80,15	-7,24	3,29	80,35	-6,80	3,18	0,50	80,13	-6,37	3,79	1,01
95	25,92	-26,75	8,14	27,34	-23,30	10,41	4,37	26,58	-23,45	11,21	4,56
96	24,78	-20,28	10,67	26,14	-18,20	11,50	2,62	25,83	-18,15	12,42	2,95

Colour	Colorimetric data measured with a spectrophotometer			Simultaneous measuring and calibration			ΔE^*_{ab} - real	Calibration precedes measuring			ΔE^*_{ab} - sing
	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real		L*-sing	a*-sing	b*-sing	
97	19,87	-17,69	1,36	20,96	-13,31	2,93	4,78	20,71	-13,05	3,23	5,07
98	34,47	-1,78	0,06	33,29	-1,45	0,53	1,31	33,10	-1,85	0,77	1,54
99	66,95	-11,78	0,9	67,00	-11,22	0,70	0,59	67,06	-11,41	1,24	0,52
100	84,68	-14,11	0,5	85,61	-13,50	1,06	1,25	85,17	-12,97	1,53	1,61
101	15,57	-8,82	1,1	17,33	-5,54	1,67	3,77	17,38	-5,57	2,50	3,97
102	66,63	-21,42	1,1	65,80	-20,16	-0,44	2,16	65,70	-20,45	0,43	1,51
103	74,69	-24,05	0,99	73,40	-22,97	-0,51	2,26	73,02	-22,85	0,50	2,11
104	50,57	-8,52	-1,31	51,47	-6,93	-1,28	1,83	50,98	-7,34	-0,79	1,35
105	24,96	-21,45	-3,88	25,48	-17,88	-1,52	4,31	24,87	-18,89	-0,99	3,86
106	89,5	-8	-0,03	89,91	-7,90	0,01	0,43	89,04	-7,27	0,00	0,87
107	78,28	-6,99	-1,42	78,87	-6,57	-1,69	0,77	78,20	-6,55	-0,97	0,63
108	76,27	-9,39	-2,48	76,98	-8,66	-1,88	1,18	76,08	-8,35	-1,24	1,63
109	41,82	-33,66	-10,54	41,30	-34,95	-15,13	4,80	40,07	-35,25	-14,15	4,32
110	13,47	-3,55	-0,46	15,67	-2,50	-0,14	2,45	15,25	-2,69	-0,48	1,98
111	85,64	-11,02	-3,87	86,78	-11,24	-3,27	1,30	85,78	-10,67	-3,05	0,90
112	55,62	-16,3	-9,34	56,25	-16,42	-9,66	0,72	55,42	-16,73	-8,92	0,64
113	74,41	-19,23	-10,85	74,67	-19,05	-11,26	0,52	73,42	-18,53	-9,76	1,63
114	44,63	-22,33	-12,21	44,27	-23,85	-15,99	4,09	43,38	-23,86	-15,08	3,48
115	64,98	-25,34	-13,59	64,98	-26,00	-14,58	1,19	63,82	-25,84	-13,82	1,28
116	35,8	-25,91	-12,3	37,26	-25,02	-13,64	2,17	35,97	-25,34	-13,44	1,29
117	55,08	-30,07	-18,19	54,22	-32,22	-22,17	4,60	53,28	-32,28	-21,52	4,38
118	84,46	-1,29	0,51	85,21	-1,61	0,87	0,89	84,70	-1,62	1,22	0,82
119	84,05	-8,05	-5,37	84,60	-8,71	-5,55	0,88	83,77	-8,19	-5,10	0,42
120	17,55	-9,69	-8,14	18,39	-8,54	-7,96	1,44	17,26	-8,41	-7,75	1,37
121	75,09	-14,85	-13,41	74,99	-15,49	-14,48	1,25	73,82	-14,81	-13,16	1,30
122	46,22	-16,7	-16,15	46,43	-17,10	-18,57	2,46	45,59	-17,31	-17,69	1,77
123	34,65	-22,41	-17,08	37,28	-21,03	-16,94	2,98	36,13	-21,50	-16,92	1,74
124	35,92	-2,36	-3,28	36,05	-2,35	-5,74	2,47	35,22	-2,54	-5,29	2,13
125	33,28	-7,89	-10,48	33,52	-6,94	-12,78	2,50	31,28	-7,47	-13,03	3,27
126	60,78	-2,18	-2,34	62,32	-2,80	-2,12	1,68	61,92	-2,89	-1,74	1,47
127	88,07	-4,84	-4,32	88,82	-5,48	-4,00	1,04	87,95	-5,08	-3,57	0,80
128	77,27	-5,51	-7,67	77,82	-5,57	-7,50	0,58	76,85	-5,35	-6,89	0,90
129	26,12	-7,6	-10,42	23,03	-7,40	-12,16	3,55	22,22	-7,67	-12,14	4,27
130	46,5	-12,86	-19,97	47,01	-13,83	-22,37	2,64	45,41	-14,44	-22,36	3,06
131	34,35	-15,69	-23,64	36,29	-14,40	-22,56	2,57	35,46	-14,67	-22,27	2,04
132	13,95	-6,52	-9,95	14,34	-5,43	-10,92	1,51	12,95	-4,52	-10,88	2,42
133	29,14	-9,05	-17,19	29,02	-7,27	-19,85	3,20	27,22	-7,78	-20,49	4,02
134	38,61	-16,21	-32,23	39,68	-17,01	-31,73	1,43	38,18	-16,19	-31,46	0,88
135	35,55	-2,44	-8,44	35,85	-2,32	-10,06	1,65	34,53	-2,78	-9,99	1,88
136	30,16	-4,21	-17,49	30,07	-2,97	-19,91	2,72	28,56	-4,03	-20,03	3,00
137	28,41	-10,54	-27,45	29,13	-7,90	-28,72	3,02	27,12	-8,05	-29,60	3,53
138	17,22	-4,06	-20,74	16,25	-4,69	-21,22	1,26	13,12	-5,09	-23,93	5,30
139	63,15	0,23	-0,42	64,10	-0,21	-0,36	1,04	63,94	-0,66	0,18	1,33
140	45,11	0,22	-10,33	46,60	1,61	-9,72	2,13	45,52	0,76	-9,37	1,17
141	24,07	-1,35	-28,46	24,11	-0,98	-30,36	1,94	22,17	-1,52	-31,40	3,50
142	18,96	2,37	-24,13	18,40	0,42	-26,24	2,93	16,61	0,15	-27,22	4,47
143	14,08	0,48	-13,51	13,38	-2,65	-16,50	4,38	12,16	-2,60	-17,19	5,17
144	7,52	0,26	-0,42	13,17	-0,51	-0,46	5,70	12,29	0,43	-0,80	4,79
145	72,89	4,49	-16,85	73,42	4,24	-16,65	0,62	72,85	3,80	-16,07	1,04
146	25,46	8,16	-39,29	23,04	8,45	-42,90	4,36	21,25	8,06	-43,78	6,16

Colour	Colorimetric data measured with a spectrophotometer			Simultaneous measuring and calibration			ΔE^*_{ab}-real	Calibration precedes measuring			ΔE^*_{ab}-sing
	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real		L*-sing	a*-sing	b*-sing	
147	13,54	0,94	-0,58	15,28	0,05	0,39	2,18	14,44	0,17	-1,20	1,34
148	33,21	19,83	-12,82	31,61	22,05	-13,55	2,83	30,37	21,19	-14,86	3,75
149	44,52	25,98	-6,76	44,01	26,20	-7,24	0,73	42,96	24,19	-8,56	2,98

5

Table 4
Average and median of ΔE_{ab} of Examples 1-6

	Number of model parameters	Weighing	Calibration beforehand	Simulta-neous calibration	Grey balancing	ΔE_{ab} average	ΔE_{ab} median
1	4	Y	----	Y	-----	2,26	1,67
2	4	Y	Y	-----	-----	2,23	1,61
3	4	Y	----	Y	Y	2,21	1,60
4	4	Y	Y	-----	Y	2,15	1,56
5	4	-----	----	Y	-----	2,91	2,15
6	20	-----	----	Y	-----	2,32	1,74

10

Table 6
Average and median of ΔE_{ab} of Examples 7-12

	Number of model parameters	Weighing	Calibration beforehand	Simultaneous calibration	Grey balancing	ΔE_{ab} average	ΔE_{ab} median
7	4	Y	----	Y	----	2,20	2,04
8	4	Y	Y	----	----	2,24	2,18
9	4	Y	----	Y	Y	2,59	2,40
10	4	Y	Y	----	Y	2,55	2,25
11	4	----	----	Y	----	3,12	3,22
12	20	----	----	Y	----	4,44	2,72

Table 5
Measuring data of Examples 7 and 8

Colour	Colorimetric data measured with a spectrophotometer			Simultaneous measuring and calibration				Calibration precedes measuring			
	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real	ΔE^*_{ab}-real	L*-sing	a*-sing	b*-sing	ΔE^*_{ab}-sing
1	34,21	16,65	16,48	34,23	14,77	19,33	1,60	34,23	14,77	19,33	1,60
2	33,18	15,57	23,9	34,04	14,44	24,83	2,03	34,03	14,53	24,77	2,10
3	35,72	17,79	33,24	34,39	14,77	31,50	2,35	34,38	14,77	31,43	2,41
4	32,08	21,48	17,81	31,48	19,18	20,39	1,72	31,61	19,49	20,44	1,67
5	37,03	23,94	32,59	38,29	20,06	33,84	0,31	38,34	20,24	33,99	0,46
6	33,59	33,8	18,02	31,05	29,59	16,98	5,16	30,93	30,41	17,07	4,95
7	33,58	32,06	24,65	33,61	28,99	26,61	1,26	33,76	29,18	27,19	1,08
8	34,29	37,55	33,64	35,96	35,04	36,93	1,62	35,97	35,19	37,25	1,94
9	45,51	17,17	16,13	45,80	15,32	17,25	0,60	45,80	15,44	17,13	0,57
10	50,32	14,45	24,96	51,21	9,16	26,71	2,45	51,40	9,57	26,90	2,31
11	48,99	16,91	36,51	50,31	9,76	38,19	2,75	50,38	9,80	38,15	2,71
12	50,54	25,58	16,78	52,81	22,78	19,78	2,39	52,72	22,71	19,85	2,41
13	52,96	22,31	32,5	54,30	16,16	35,87	2,05	54,36	16,21	36,05	2,16
14	45,62	32,24	17,62	45,13	28,98	18,54	2,46	45,22	29,10	18,45	2,39
15	50,63	34,07	24,3	51,79	28,81	27,34	2,90	51,95	29,53	27,21	2,21
16	51,8	37,11	36,22	53,99	32,45	41,31	2,55	54,22	33,08	41,63	2,96
17	18,88	15,9	9,19	20,03	13,39	9,41	1,28	20,14	13,72	9,38	1,16
18	29,15	20,6	24,53	29,32	17,30	27,26	1,81	29,89	17,61	27,27	1,46
19	18,05	-5,02	-15,56	15,18	-1,07	-16,41	4,63	15,16	-0,97	-16,55	4,53
20	31,51	51,33	31,58	31,74	45,45	29,20	3,13	31,55	46,96	29,31	3,76
21	26,8	24,49	19,3	26,48	23,43	21,15	1,75	26,51	23,84	21,86	2,32
22	44,94	32,01	44,81	48,16	27,24	47,26	1,69	48,35	27,55	47,82	2,05
23	25,5	9,73	17,32	25,86	7,72	15,96	1,60	25,90	7,75	16,07	1,51
24	35,52	26,71	26,01	35,96	23,77	28,12	0,84	35,94	24,31	28,40	1,30
25	43,32	8,31	32,85	42,79	2,20	32,05	1,46	42,87	2,30	31,93	1,38
26	39,47	42,54	30,09	40,36	50,78	39,66	5,41	40,49	51,04	39,63	5,65
27	47,46	20,61	24,89	47,98	16,46	26,79	1,64	47,99	16,64	26,88	1,58
28	67,01	13,65	34,47	68,44	8,92	37,58	2,29	68,36	8,83	37,57	2,20

5

Claims

1. Method of determining a colour formula for matching a selected colour measured with an electronic imaging device, which method comprises the

5 following steps:

a) an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colours, the colorimetric data of each of the calibration colours being known;

b) at the same time or in a next step the selected colour is measured with

10 the aid of the electronic imaging device;

c) using a mathematical model, parameters are calculated for converting the measured colour signals of the calibration colours to the known colorimetric data;

d) using the mathematical model and the calculated parameters, the

15 colour signals of the measured selected colour are converted to colorimetric data; and

e) using a databank, the colour formula of which the colorimetric data most closely matches the calculated colorimetric data of the measured selected colour is determined.

20

2. A method according to claim 1, characterised in that the calibration colours are distributed over the entire colorimetric colour space.

3. A method according to claim 2, characterised in that the calibration colours

25 are distributed in the vicinity of the selected colour.

4. A method according to any of claims 1-3, characterised in that the calibration colours in the vicinity of the selected colour are given greater weight when calculating the model parameters.

30

5. A method according to any of claims 1-3, characterised in that the electronic imaging device is a flatbed scanner.

6. A method according to one or more of preceding claims 1-3, characterised in that the electronic imaging device is a digital camera.

5 7. A method according to one or more of claims 1-3, characterised in that the measurement of the calibration colours and the selected colour takes place simultaneously.

8. A method according to any of claims 1-3, characterised in that texture
10 parameters can be calculated from the recording of the selected colour and that by using a databank the colour formula can be determined of which the texture parameters most closely match the calculated texture parameters of the measured selected colour.

15 9. A method according to claim 8, characterised in that a ruler is provided on the calibration pattern.

10. A method of determining a texture and/or colour formula for matching a selected colour and/or texture of a selected material in which
20 a) the colour of the selected material is measured with a spectrophotometer or a tri-stimulus meter;
 b) the texture of the selected material is measured with an electronic imaging device; and
 c) the measured colour and texture data are used to determine, in a
25 databank, the texture and/or colour formula of which the colorimetric data and the texture data most closely match those of the selected material.

11. A method according to any one of claims 1-3, 9 or 10, characterised in that
30 the method is carried out in the car repair industry.

12. A method according to any one of claims 1-3, 9 or 10, characterised in that additional information is provided during recording of the selected colour with the electronic imaging device.

5   13. A method of determining the colour difference of a selected colour measured with an electronic imaging device compared to a standard colour sample, which method comprises the following steps:

a)   an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colours, the colorimetric data of each

10   of the calibration colours being known;

b)   at the same time or in a next step the selected colour is measured with the aid of the electronic imaging device;

c)   using a mathematical model, parameters are calculated for converting the measured colour signals of the calibration colours to the known

15   colorimetric data;

d)   using the mathematical model and the calculated parameters, the colour signals of the measured selected colour are converted to colorimetric data; and

e)   the colorimetric data of the selected colour are compared to the

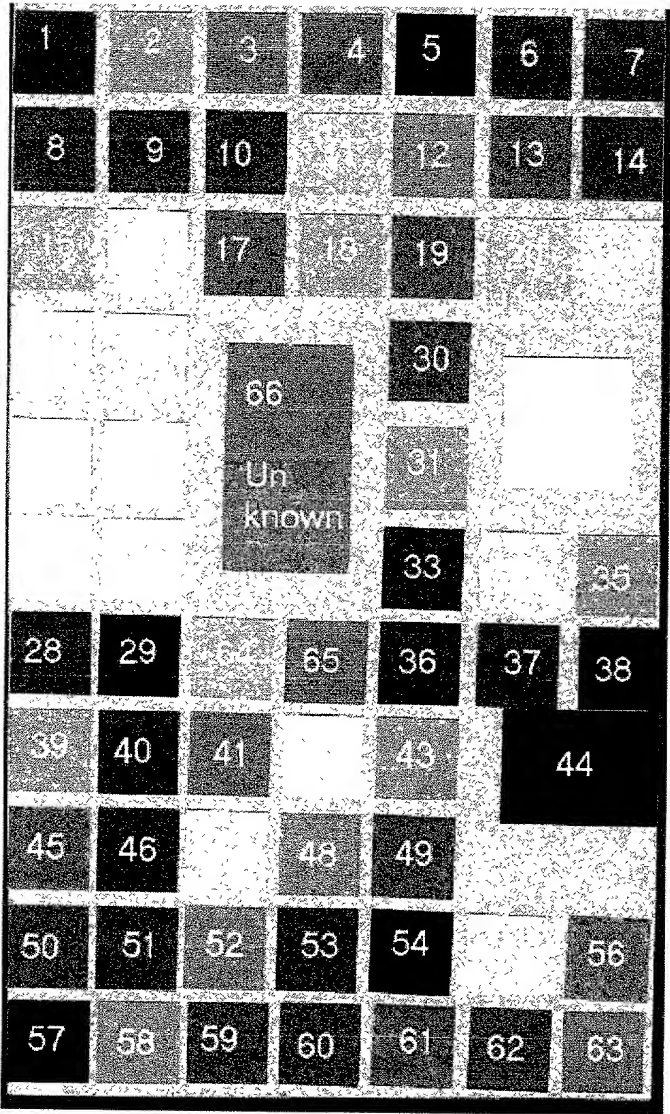20   colorimetric data of a standard colour sample.

Abstract

The invention pertains to a method of determining a colour formula for matching a selected colour measured with an electronic imaging device, which method

5   comprises the following steps:

a)   an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colours, the colorimetric data of each of the calibration colours being known;

b)   at the same time or in a next step the selected colour is measured with
10   the aid of the electronic imaging device;

c)   using a mathematical model, parameters are calculated for converting the measured colour signals of the calibration colours to the known colorimetric data;

d)   using the mathematical model and the calculated parameters, the colour
15   signals of the measured selected colour are converted to colorimetric data; and

e)   using a databank, the colour formula is determined of which the colorimetric data most closely matches the calculated colorimetric data of the measured selected colour.

20   The invention also comprises a method of determining a colour formula for matching a selected colour of textured materials such as special effect paints and to a method of determining the colour difference of a selected colour measured with an electronic imaging device compared to a standard colour sample.

25   The invention has the advantage that it is possible to make use of inexpensive consumer electronics. The method according to the invention also makes it possible to measure a specific attribute of the colour appearance, the so-called texture.
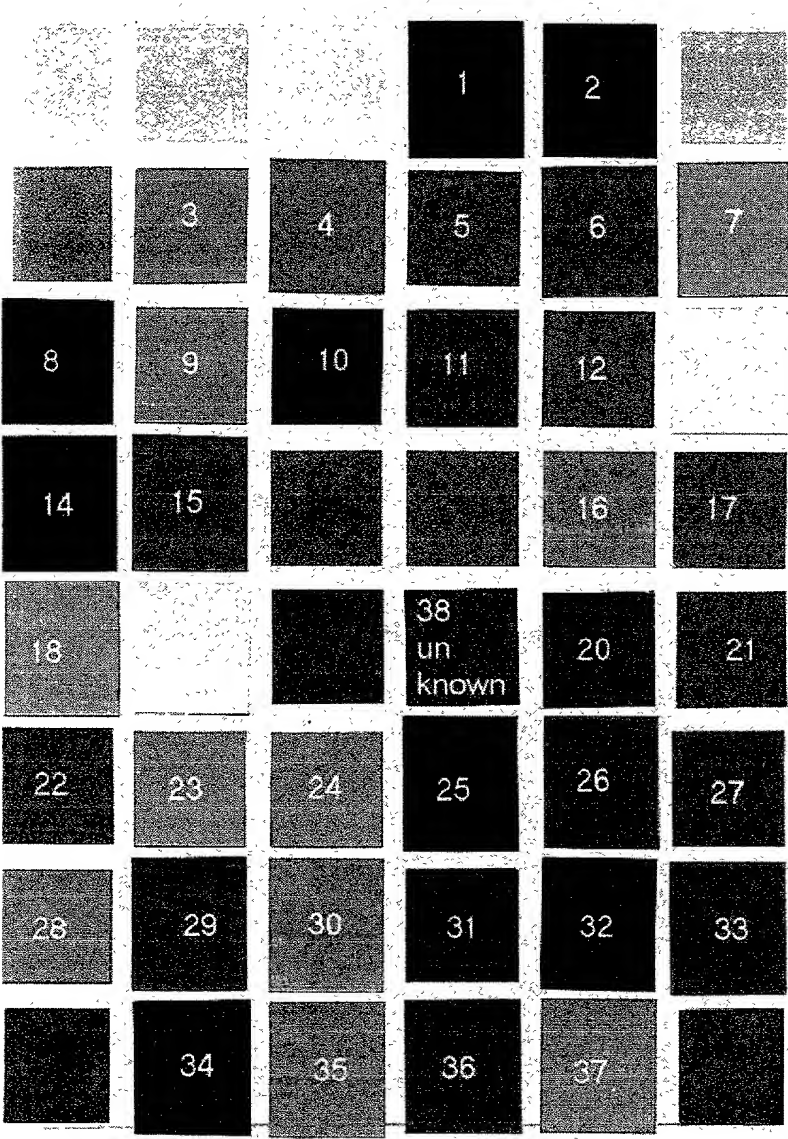
Figure 1

5   Calibration pattern 1

Figure 2

Calibration pattern 2

5

DECLARATION AND POWER OF ATTORNEY

As a below named inventor, I hereby declare that:

My residence/post office address and citizenship are as stated below next to my name;

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled: <u>METHODS APPLYING COLOUR MEASUREMENT BY MEANS OF AN ELECTRONIC IMAGING DEVICE</u>

the specification of which is attached hereto unless the following box is checked:

( ) was filed on _____ as US Application Serial No. or PCT International Application Number _____ and was amended on_____

I hereby state that I have reviewed and understood the contents of the above-identified specification, including the claims, as amended by any amendment(s) referred to above. I acknowledge the duty to disclose all information which is material to patentability as defined in 37 CFR 1.56.

Foreign Application(s) and/or Claim of Foreign Priority

I hereby claim foreign priority benefits under Title 35, United States Code Section 119 of any foreign application(s) for patent or inventor(s) certificate listed below and have also identified below any foreign application for patent or inventor(s) certificate having a filing date before that of the application on which priority is claimed:

COUNTRY	APPLICATION NUMBER	DATE FILED	PRIORITY CLAIMED
Europe	99203244.1	10/5/1999	YES: X NO:
			YES: NO:

Provisional Application

I hereby claim the benefit under Title 35, United States Code Section 119(e) of any United States provisional application(s) listed below:

APPLICATION SERIAL	FILING DATE

U.S. Priority Claim

I hereby claim the benefit under Title 35, United States Code, Section 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code Section

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112, I acknowledge the duty to disclose material information as defined in Title 37, Code of Federal Regulations, Section 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application:

APPLICATION SERIAL NUMBER	FILING DATE	STATUS(patented/pend ing/abandoned)

POWER OF ATTORNEY: As a named inventor, I hereby appoint the following as my attorneys of record, with full power of substitution and revocation, to prosecute this application and to transact all business in the Patent Office:

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I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

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